The 13th International Conference "ZABABAKHIN SCIENTIFIC TALKS" RUSSIAN FEDERAL NUCLEAR CENTER – ZABABAKHIN ALL-RUSSIA RESEARCH INSTITUTE OF TECHNICAL PHYSICS (RFNC-VNIITF) March 20-24, 2017 Snezhinsk, Chelyabinsk region, Russia

### **Hybrid Numerical Model of Acceleration of Charged Particles on a Shock Wave Front**

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The research was supported by the Russian Science Foundation (RSF) under Grant 16-11-10028 and Russian Foundation for Basic Research under Grants 16-01-00209 and 16-07-00916.

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#### **Introduction.** Models of collisionless plasma. Hybrid models.





#### **Cosmic rays**



Left: Victor Hess before his balloon flight, during which he observed cosmic ray intensity increasing with altitude. Right: Hess's balloon.





#### Hybrid numerical model of acceleration of charged particles on a shock wave front 1.1 Geometry and assumptions

- > 2D problem in Cartesian coordinates;
- plasma consists of hydrogen ions and electrons;
- > uniform magnetic field;
- > quasineutral plasma.



Motion equations for ions:

$$\begin{aligned} &\frac{d\vec{r}}{dt} = \vec{u}_{\alpha}, \\ &m_{\alpha} \frac{d\vec{u}_{\alpha}}{dt} = Z_{\alpha} e \bigg( \vec{E} + \frac{1}{c} \vec{u}_{\alpha} \times \vec{B} \bigg) + \vec{R}_{\alpha}. \end{aligned}$$

Here  $Z_{\alpha}$  is an ion charge of sort  $\alpha$  ,  $\vec{R}_{\alpha}$  is a friction force between ions of sort  $\alpha$  and electrons.

A density and an average ion velocity:

$$n_{\alpha} = \int f_{\alpha} d\vec{u}_{\alpha},$$
$$\vec{V}_{\alpha} = \frac{1}{n_{\alpha}} \int f_{\alpha} \vec{u}_{\alpha} d\vec{u}_{\alpha}.$$

Motion equations for electrons:

$$m_e \left( \frac{\partial \vec{V_e}}{\partial t} + \left( \vec{V_e} \cdot \nabla \right) \vec{V_e} \right) = -e \left( \vec{E} + \frac{1}{c} \vec{V_e} \times \vec{B} \right) - \frac{\nabla p_e}{n_e} + \vec{R}_e,$$
$$n_e \left( \frac{\partial T_e}{\partial t} + \left( \vec{V_e} \cdot \nabla \right) T_e \right) + (\gamma - 1) p_e \nabla \cdot \vec{V_e} = (\gamma - 1) (Q_e - \nabla \cdot \vec{q}_e).$$

Maxwell equations:

$$\nabla \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}, \quad \nabla \times \vec{B} = \frac{4\pi}{c} \vec{j}, \quad \nabla \cdot \vec{B} = 0.$$

Here  $\vec{j}$  is a current density which in case of multicomponent plasma is as follows

$$\vec{j} = e \left( \sum_{\alpha} Z_{\alpha} n_{\alpha} \vec{V}_{\alpha} - n_e \vec{V}_e \right).$$

Plasma is quasineutral, i.e.  $n_e = \sum Z_{\alpha} n_{\alpha}$ ;

 $\vec{q}_e = -k_1 \nabla T_e$  where  $k_1$  is a coefficient of electron heat conductivity,  $\vec{V} = (V_x, V_y, V_z)$  is an average ion velocity,  $Q_e = \frac{j^2}{\sigma}, \sigma = \frac{n_e e^2}{m_e v}$  and friction forces in plasma are  $\vec{R}_1 = -\frac{Z_1 e}{\sigma} \vec{j}, \ \vec{R}_2 = -\frac{Z_2 e}{\sigma} \vec{j}, \ \vec{R}_e = -\frac{n_1}{n_e} \vec{R}_1 - \frac{n_2}{n_e} \vec{R}_2.$ **1.3 Normalization** 

$$n_{0}, B_{0}, V_{A} = \frac{B_{0}}{\sqrt{4\pi m_{i} n_{0}}}, T_{0} = \frac{B_{0}^{2}}{8\pi n_{0}}, \omega_{pi} = \sqrt{\frac{4\pi n_{0} e^{2}}{m_{i}}}, L = \frac{c}{\omega_{pi}},$$
$$t_{0} = \frac{L}{V_{A}}, E_{0} = \frac{1}{c} B_{0} V_{A}, \beta = \frac{m_{e}}{m_{i}}.$$

#### Hybrid numerical model of acceleration of charged particles on a shock wave front 1.4 Equations in dimensionless form

Ion motion equations:

$$\frac{d\vec{r}}{dt} = \vec{u}_{\alpha}, \quad \frac{M_{\alpha}}{Z_{\alpha}} \frac{d\vec{u}_{\alpha}}{dt} = \vec{E} + \vec{u}_{\alpha} \times \vec{B} - \zeta \frac{1}{n_e} \nabla \times \vec{B}.$$

Motion equations for electrons:

$$\beta \left( \frac{\partial \vec{V_e}}{\partial t} + \left( \vec{V_e} \cdot \nabla \right) \vec{V_e} \right) = -\vec{E} - \vec{V_e} \times \vec{B} - \frac{1}{2n_e} \nabla p_e + \zeta \frac{1}{n_e} \nabla \times \vec{B},$$

$$n_e \left( \frac{\partial T_e}{\partial t} + \left( \vec{V_e} \cdot \nabla \right) T_e \right) + (\gamma - 1) p_e \nabla \cdot \vec{V_e} = (\gamma - 1) \left( 2\zeta \frac{1}{n_e} \left( \nabla \times \vec{B} \right)^2 + \nabla \cdot \left( \zeta_1 \nabla T_e \right) \right).$$

Maxwell equations:

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}, \quad \nabla \times \vec{B} = \vec{j}, \quad \nabla \cdot \vec{B} = 0.$$

Here  $M_{\alpha} = \frac{m_{\alpha}}{m_i}, \zeta = \frac{m_e vc}{B_0 e}, \zeta_1 = \frac{4\pi e \kappa_1}{B_0 c}.$ 

#### Hybrid numerical model of shock waves in collisionless plasma 1.5 Initial data and boundary conditions

Initial data of the background plasma:

 $t = 0: \quad n = n_0 = const, \quad B_z = B_0 = const, \quad B_x = B_y = 0,$ 

$$T = T_0, \quad v_x = u_0, \quad v_y = v_z = 0, \quad E_x = E_y = E_z = 0.$$

Solution area:

$$0 \le x \le x_{\max}, \quad 0 \le y \le y_{\max}.$$

Boundary conditions:



a) for particles: x=0- conditions of the incoming flow,  $x = x_{max} -$  conditions of reflection,  $y=0, y = y_{max} -$  periodical conditions;

b) 
$$x = 0, x = x_{max}$$
:  $E_x = 0, \ \partial E_y / \partial x = \partial E_z / \partial x = 0, \ \partial n / \partial x = 0;$   
 $y = 0, y = y_{max}$ : periodical conditions.



$$\vec{V}_{e}^{m+1} = \vec{V}^{m+1} - \frac{1}{n^{m+1}} \nabla \times \vec{B}^{m}$$

$$\vec{B}^{m+1} - \vec{B}^{m} = \nabla \times \left(\vec{V}_{e}^{m} \times \vec{B}^{m+1}\right) - \nabla \times \left(\frac{\zeta}{n_{e}} \nabla \times \vec{B}^{m+1}\right) + \nabla \times \left[\beta\left(\frac{\partial \vec{V}_{e}}{\partial t} + \left(\vec{V}_{e} \cdot \nabla\right)\vec{V}_{e}\right) + \frac{1}{2n_{e}} \nabla p_{e}\right]$$

$$\vec{E}^{m+1} = -\vec{V}_{e} \times \vec{B}^{m+1} + \frac{\zeta}{n_{e}} \nabla \times \vec{B}^{m+1} - \beta\left(\frac{\partial \vec{V}_{e}}{\partial t} + \left(\vec{V}_{e} \cdot \nabla\right)\vec{V}_{e}\right) + \frac{1}{2n_{e}} \nabla p_{e}$$

$$\vec{T}_{e}^{m+1} - T_{e}^{m} + \left(\vec{V} \cdot \nabla\right)T_{e}^{m+1} + \frac{\zeta}{\tau} + \left(\vec{V} \cdot \nabla\right)T_{e}^{m+1} + \frac{\zeta}{\tau} + \left(\gamma - 1\right)n^{m+1}T_{e}^{m+1} \nabla \cdot \vec{V}_{e}^{m+1} = (\gamma - 1)\left(Q_{e}^{m+1} - \nabla \cdot q_{e}^{m+1}\right)$$
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# Hybrid numerical model of acceleration of charged particles on a shock wave front 1.6 Algorithm R(y)

Here 
$$\overline{R}(\vec{r}) = \overline{R}(x)\overline{R}(y)$$
 and  
 $\overline{R}(f) = \begin{cases} 1 - \frac{|f|}{h}, & |f| \leq h, \\ 0, & |f| > h, & where \quad f = \{x, y\}. \end{cases}$ 

There is a uniform mesh with steps  $h_1, h_2$  by axis x, y, respectively. Grid functions are set as follows:

$$B_{z} \Rightarrow (x_{i} = ih_{1}, y_{k} = kh_{2}),$$
  

$$V_{x}, V_{ex}, E_{x}, B_{y} \Rightarrow (x_{i}, y_{k-1/2} = (k - 0.5)h_{2}),$$
  

$$V_{y}, V_{ey}, E_{y}, B_{x} \Rightarrow (x_{i-1/2} = (i - 0.5)h_{1}, y_{k}),$$
  

$$n, T_{e}, V_{z}, V_{ez}, E_{z} \Rightarrow (x_{i-1/2}, y_{k-1/2}).$$



Fig. 1. Phase space of ions at times t=8.0 (a), 9.0 (b). Here  $v_0 = 1$ ,  $M_A = 1.9$ .



**Fig. 2.** Phase space of ions at times t=3, 5, 11, 14. Here  $v_0 = 1.5$ ,  $M_A = 2.8$ . The ion reflection by a shock wave along with the ion rotation on the Larmor radius and the quasistationary structure formation due to the continuous reflection of the oncoming plasma flow by the shock wave and its rotation in the external magnetic field.



Fig. 3. Magnetic field  $B_z$  and phase space of ions at times t = 5,9,  $v_0 = 5$ ,  $M_A = 15$ .



Fig. 4. Phase space of ions at time t=200.





#### Conclusion

- > the new 2D numerical model of the shock wave generation and structure to study the acceleration mechanism of cosmic ray particles on its front has been made;
- the new numerical algorithm has been developed;
- > the further modification of the model to solve problems which are close to the real studied phenomena (acceleration of cosmic rays) is in future plans.



## Thank you for your attention!



